Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application. These amendments introduce no new matter and support for the amendment is replete throughout the specification and claims as originally filed. These amendments are made without prejudice and are not to be construed as abandonment of the previously claimed subject matter, or agreement with any objection or rejection of record.

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Listing of Claims:

1-9 CANCELLED

10. (**ORIGINAL**): A method of repairing a damaged nerve in a living organism comprising: selecting one or more axons in said damaged nerve;

harvesting a donor axon segment;

positioning said donor axon segment at a severed location of a selected axon; and inducing fusion of said donor axon segment.

11. (ORIGINAL): The method of claim 10 further comprising: cutting one or more ends of said donor axon and/or said selected axon.

12. (**ORIGINAL**): The method of claim **10** further comprising:

wherein said positioning comprises:

applying a dielectrophoresis signal in proximity of one or more of said donor axon or said selected axon.

13. (**ORIGINAL**): The method of claim **10** further comprising:

wherein said inducing comprises:

applying a electric signal in proximity of one or more of said donor axon or said selected axon.

14. (**ORIGINAL**): The method of claim **10** further comprising:

digesting one or more nerve portions to allow manipulation of individual axons.

15. (ORIGINAL): The method of claim 10 further comprising:

using a MEMS axon surgical platform enabling precise manipulation of axons of less than one and up to a few microns in diameter.

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- **16.** (ORIGINAL): The method of claim 10 wherein said living animal comprises a human.
- 17. (ORIGINAL): The method of claim 10 wherein said living animal comprises a mammal.
- **18. (ORIGINAL):** The method of claim **15** further wherein: said MEMS axon surgical platform enables manipulation of axons directed by a human surgeon.
- 19. (CURRENTLY AMENDED): A method of repairing a damaged nerve in a living organism comprising:

selecting one or more severed axons in said damaged nerve;

positioning one or more of said selected severed axons in close proximity to one or more corresponding severed axons on another side of said damaged nerve; and inducing fusion of axons placed in proximity.

said one or more corresponding severed axons are not necessarily matched to axon segments to which they were attached before becoming severed; and cutting said one or more severed axons prior to said inducing.

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- **69.** (**NEW**): The method of claim **19** further wherein:
 - said selecting, positioning, and inducing are performed without determining whether a corresponding severed axons is matched to axon segments to which they were attached before becoming severed.
- **70.** (**NEW**): The method of claim **19** further comprising: using a nanoknife to cut said one or more severed axons prior to said inducing.
- 71. (NEW): The method of claim 19 further comprising:

placing a three-dimensional microstructure over an area containing said axon;

said three-dimensional microstructure comprises:

one or more nanoknives used for cutting axons;

one or more actuators for moving said nanoknives; and

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one or more effector electrodes for moving axons.

said three-dimensional microstructure is smaller than approximately one cubic millimeter.

72. (NEW): The method of claim **71** further wherein:

said three-dimensional microstructure is smaller than approximately 100 cubic millimeters.

73. (NEW): The method of claim 71 further comprising:

placing said three-dimensional microstructure in a surgical frame, said surgical frame comprising one or more gaskets for holding one or more nerves to be repaired;

said three-dimensional microstructure and said surgical frame comprising one or more microfluidic channels for delivering reagents; and

said three-dimensional microstructure comprising one or more waveguides to enable optical monitoring, visualization, and /or use of light sources.

74. (NEW): The method of claim **71** further comprising:

moving an axon segment using a pin/probe and plate electrode pair operably connected with said microstructure such that a region of strongest field is towards the pin electrode thereby stretching an axon towards said pin/probe electrode.

75. (NEW): The method of claim 19 further comprising:

moving an axon segment by precisely positioning arrangements of micro-electrodes near to said axon segment; and

applying electrical signals precisely to particular electrodes to effect precise movements and/or manipulations.

76. (**NEW**): The method of claim **75** wherein said precisely positioning of arrangements of electrodes comprises positioning an addressable grid of electrodes above and/or below said axon segment and further comprising:

observing said axon segment in relation to said addressable grid of electrodes;

selecting one or more electrodes that will effect a desired movement of said axon segment; and

- applying a predetermined energy signal to said one or more electrodes; and further comprising:
- observing an induced movement of said axon segment in relation to said addressable grid of electrodes;
- selecting an additional one or more electrodes that will effect a desired further movement of said axon segment; and
- applying a predetermined energy signal to said additional one or more electrodes.
- 77. (NEW): A system of repairing a damaged nerve in a living organism by separately repairing one or more axons comprising:
 - a surgical frame container for isolating a damaged nerve portion in a living subject; said surgical frame comprising:
 - one or more nerve gaskets for holding nerve portions in said frame container;
 - one or more wave guides for providing illumination within said frame container;
 - a plurality of fluid inflow and outflow channels able to maintain a desired medium with desired properties in said surgical frame container;
 - an opening able to receive a three-dimensional microsurgery platform and allowing access to said platform to a manipulator;

the microsurgery platform comprising:

- a nanoknife;
- one or more actuators for moving the nanoknife up and down in order to cut axons and axon segments;
- one or more electrodes positioned near said nanoknife for delivering controlled electrical signals in proximity to said nanoknife, further wherein
- said one or more electrodes are connectable to an external signal source thereby able to deliver electric signals to orient and move axons and axon segments thereby selecting one or more severed axons in said damaged nerve and positioning one or more of said selected severed axons in close proximity to one or more corresponding severed axons on another side of said damaged nerve; and

said one or more electrodes are connectable to an external signal source thereby able to deliver electric signals inducing fusion of axons segments placed in proximity to said electrodes.

78. (**NEW**): The system of claim **77** further wherein:

- one or more of said electrodes comprise an electrode array, each having at least two addressable pin/probe and/or plate electrodes.
- said one or more electrodes have at least three separable modes of operation comprising:
 - a positioning mode for moving cells and/or cell components;
 - a joining mode for moving two or more cells and/or cell components in proximity to each other; and
 - a fusion mode for inducing fusion of said cells and/or cell components.